



techhose

QUALITY CONNECTIONS

Hydraulics

Pneumatics
& Vacuum

Industrial

Compressed Air
& Ring Main

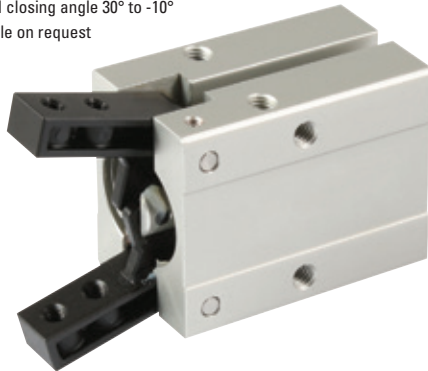
Process &
Instrumentation

Pneumatic & Vacuum

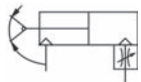
Grippers & Drives

Pneumatic Grippers

- Uses a single piston structure to generate a large gripping force
- Integrated variable flow valve to conveniently adjust the speed of opening and closing of the fingers
- Precise positioning accuracy when gripping components
- Body profile adapted with grooves for mounting sensor switches
- Integrated magnet for added control
- Gripping jaw opening and closing angle 30° to -10°
- Single acting N/O available on request
- Interchangeability: SMC



KHFY: Double Acting



Double Acting, Angular Style

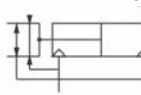
0415	Thread	Bore mm	Optimum Gripping Points Length mm
KHFY6	M3 x 0.5	6	30
KHFY10	M3 x 0.5	10	30
KHFY16	M5 x 0.8	16	40
KHFY20	M5 x 0.8	20	60
KHFY25	M5 x 0.8	25	70
KHFY32	M5 x 0.8	32	85

Tech Sheet 20470

- Integrated linear guide rail for high precision and rigidity
- Positioning pin at the base of the unit to prevent deviation of the rail and body
- Deeper hole on the body to improve precision and consistency when dismounting and positioning
- Variable positioning jaws
- Body profile adapted with grooves for mounting sensor switches
- Other finger types available on request
- Single acting N/O and N/C available on request
- Interchangeability: SMC



KHfZ: Double Acting



Double Acting, Parallel Style

0415	Thread	Bore mm	Optimum Gripping Points Length mm	Open Diameter mm	Closed Diameter mm
KHfZ10	M3 x 0.5	6	5-50	15.5	11.5
KHfZ16	M5 x 0.8	16	5-55	21.0	15.0
KHfZ20	M5 x 0.8	20	5-80	26.5	16.5
KHfZ25	M5 x 0.8	25	5-100	33.5	19.5

Tech Sheet 20471

How to select product:

Please select pneumatic finger according to the following steps:

The selection of the effective gripping force → the confirmation of the gripping point → the confirmation of the external force put on the gripping jaw.

The selection of the gripping force:
The gripping work-pieces shown, on the impact condition of ordinary handling state, taking safety coefficient $a=4$, have a gripping force that is more than 10-20 times of the mass of the gripped objects

$\mu = 0.2$	$\mu = 0.1$
$F = \frac{mg}{2 \times 0.2} \times 4$	$F = \frac{mg}{2 \times 0.1} \times 4$
$= 10 \times mg$	$= 20 \times mg$
10 times of the mass of the gripped objects	20 times of the mass of the gripped objects

F: gripping force (N)

μ : friction coefficient between fittings and work-pieces

m: mass of work-pieces

g: acceleration of gravity ($=9.8\text{m/s}^2$)

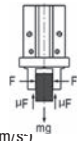
The condition that the work-pieces won't drop is $2 \times \mu F > mg$, so:

$$F > \frac{mg}{2 \times \mu}$$

Safety coefficient is a, so F is:

$$F = \frac{mg}{2 \times \mu} \times a$$

Note: if the friction coefficient $\mu > 0.2$, for safety, please also select clamping force according to the principle of 10-20 times of the mass of the clamped objects. As for large acceleration and shock, it requires for greater safety coefficient.



Slim profile for discreet safe mounting to grippers.

Sensor Switch, Two-line, N/O

0415	Connection	Connecting Cable	Length Metres
KDS1-H-C08	Straight	M8 Quick Joint	0.15
KDS1-H-020	Straight	-	2
KDS1-H-030	Straight	-	3
KDS1-H-050	Straight	-	5
KDS1-HL-C08	90°	M8 Quick Joint	0.15
KDS1-HL-020	90°	-	2
KDS1-HL-030	90°	-	3
KDS1-HL-050	90° Connection	-	5

Tech Sheet 20472

Sensor Switch, Three-line NPN with No Contact (Current Flows In), N/O

0415	Connection	Connecting Cable	Length Metres
KDS1-H-N-C08	Straight	M8 Quick Joint	0.15
KDS1-H-N-020	Straight	-	2
KDS1-H-N-030	Straight	-	3
KDS1-H-N-050	Straight	-	5
KDS1-HL-N-C08	90°	M8 Quick Joint	0.15
KDS1-HL-N-020	90°	-	2
KDS1-HL-N-030	90°	-	3
KDS1-HL-N-050	90°	-	5

Tech Sheet 20472

Sensor Switch, Three-line PNP with No Contact (Current Flows Out), N/O

0415	Connection	Connecting Cable	Length Metres
KDS1-H-P-C08	Straight	M8 Quick Joint	0.15
KDS1-H-P-020	Straight	-	2
KDS1-H-P-030	Straight	-	3
KDS1-H-P-050	Straight	-	5
KDS1-HL-P-C08	90°	M8 Quick Joint	0.15
KDS1-HL-P-020	90°	-	2
KDS1-HL-P-030	90°	-	3
KDS1-HL-P-050	90°	-	5

Tech Sheet 20472

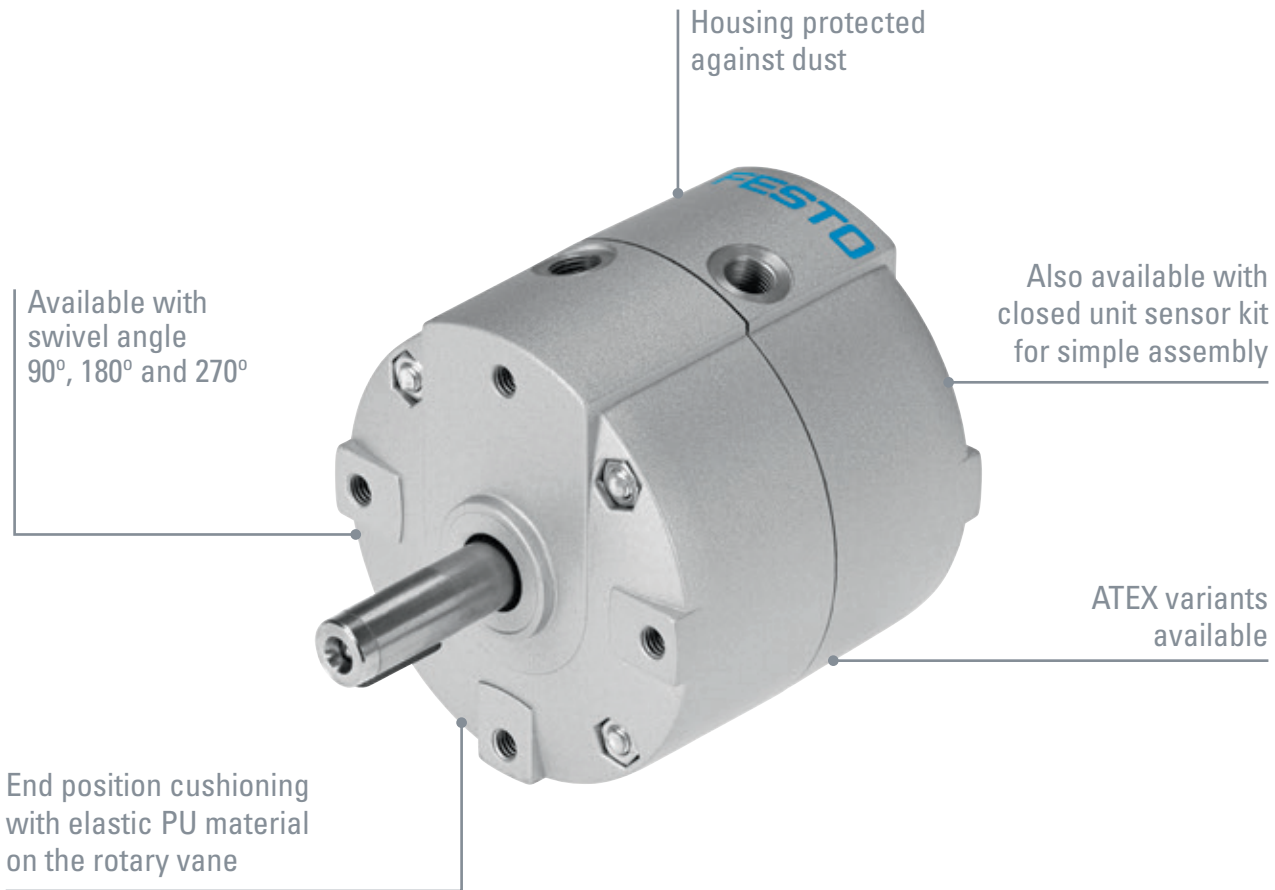
CYLINDERS

For the full range and more information, please contact one of our sales team.

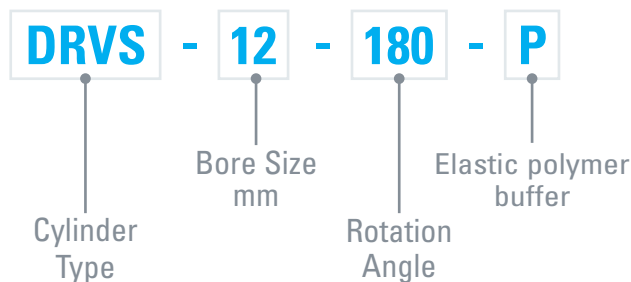
DRVS SEMI-ROTARY VANE DRIVE



Features



Product Description



SEMI-ROTARY DRIVES, DRVS

FESTO



Rotary Vane, Double Acting

- Modern and compact design
- Lighter than other semi-rotary drives
- Housing protected against splash water and dust
- Selected types in accordance with ATEX directive for potentially explosive atmospheres

Ambient Temperature:
-10°C to +60°C

Working Pressure:
3.5 to 8 bar (Size: 6, 8mm)
2.5 to 8 bar (Size: 12, 16mm)
2 to 8 bar (Size: 25, 32, 40mm)



Elastic Cushioning Rings, M3 Connection

0009	Size	Nominal Swivel Angle	Manufacturer's Code
1845706	6	90°	DRVS-6-90-P
1845707	6	180°	DRVS-6-180-P
1845708	8	90°	DRVS-8-90-P
1845709	8	180°	DRVS-8-180-P

Tech Sheet 20564

Elastic Cushioning Rings, M5 Connection

0009	Size	Nominal Swivel Angle	Manufacturer's Code
1845710	12	90°	DRVS-12-90-P
1845711	12	180°	DRVS-12-180-P
1845712	12	270°	DRVS-12-270-P
1845713	16	90°	DRVS-16-90-P
1845714	16	180°	DRVS-16-180-P
1845715	16	270°	DRVS-16-270-P
1845716	25	90°	DRVS-25-90-P
1845717	25	180°	DRVS-25-180-P
1845718	25	270°	DRVS-25-270-P

Tech Sheet 71599



Position Sensor

0009	Weight	For Drives	Type
2619969	25g	DSM 6, DRVS 6	SRBS-Q12-6-E270-EP-1-S-M8

Elastic Cushioning Rings, G1/8 Connection

0009	Size	Nominal Swivel Angle	Manufacturer's Code
1845719	32	90°	DRVS-32-90-P
1845720	32	180°	DRVS-32-180-P
1845721	32	270°	DRVS-32-270-P
1845722	40	90°	DRVS-40-90-P
1845723	40	180°	DRVS-40-180-P
1845724	40	270°	DRVS-40-270-P

Tech Sheet 71600

FESTO



For **Festo MS Series**
see page **658**